

Grimoire of curvature sign conventions, conditions, operators, and examples

Because conventions are confusing, I state mine, how they relate to other conventions and what happens on spaces of constant sectional curvature.

Throughout this note we fix a Riemannian manifold (M, g) of dimension n and denote by (e_i) an orthonormal basis of $T := T_p M$ for some $p \in M$.

Some definitions

The Riemannian curvature tensor. Given any affine connection ∇ on a vector bundle $EM \rightarrow M$, its *curvature* is the section $R^\nabla \in \Omega^2(M, \text{End } EM)$ given by

$$R^\nabla(X, Y) = [\nabla_X, \nabla_Y] - \nabla_{[X, Y]}.$$

In particular, if ∇ is the Levi-Civita connection on T of a Riemannian metric g , then $R = R^\nabla$ is the *Riemannian curvature tensor*. We may lower its indices via the metric as

$$R(X, Y, Z, W) = g(R(X, Y)Z, W).$$

We call this convention for R the *forward convention* and shall use it unless otherwise stated. The other common convention, which we call the *backward convention*¹, is $R^\nabla(X, Y) = \nabla_{[X, Y]} - [\nabla_X, \nabla_Y]$, which we see for example in [1, 2, 3, 6, 13].

Sectional curvature. The *sectional curvature* of a Riemannian metric is determined by R by

$$\text{sec}(X \wedge Y) = \frac{R(X, Y, Y, X)}{g(X, X)g(Y, Y) - g(X, Y)^2}$$

and depends only on the two-plane spanned by X and Y . There is only one convention for sec , namely the one where the round sphere $S^n(r)$ of radius r has *positive* constant sectional curvature $\text{sec} \equiv r^{-2}$. (Correspondingly, hyperbolic space has *negative* constant sectional curvature). The Riemannian curvature tensor of a metric of constant sectional curvature $\text{sec} \equiv k$ has the form

$$R(X, Y)Z = k(g(Y, Z)X - g(X, Z)Y).$$

For the backward convention, the correct formulae read

$$\text{sec}(X \wedge Y) = \frac{R(X, Y, X, Y)}{g(X, X)g(Y, Y) - g(X, Y)^2}$$

as well as

$$R(X, Y)Z = k(g(X, Z)Y - g(Y, Z)X).$$

Note that the formula in [1, Prop. 1.88] has a sign error.

¹For lack of a better name. This is not meant to be derogatory.

The Kulkarni–Nomizu product. For symmetric 2-tensors $h_1, h_2 \in \text{Sym}^2$, their *Kulkarni–Nomizu product* is the 4-tensor $h_1 \otimes h_2 \in \text{Sym}^2 \Lambda^2$ given by

$$(h_1 \otimes h_2)(X, Y, Z, W) = h_1(X, Z)h_2(Y, W) + h_1(Y, W)h_2(X, Z) \\ - h_1(X, W)h_2(Y, Z) - h_1(Y, Z)h_2(X, W).$$

The same convention is used in [1, 3]. $h_1 \otimes h_2$ is always an algebraic curvature tensor (that is, it satisfies the first Bianchi identity) – moreover, on a space of $\text{sec} \equiv k$, the curvature tensor has the form

$$R = -\frac{k}{2}g \otimes g,$$

or in the backward convention

$$R = \frac{k}{2}g \otimes g.$$

Ricci and scalar curvature. One may contract the Riemannian curvature tensor R to obtain the *Ricci tensor*

$$\text{Ric}(X, Y) = \sum_i R(e_i, X, Y, e_i) = \text{tr}(Z \mapsto R(Z, X)Y).$$

Contracting with the metric yields the *scalar curvature*

$$\text{scal} = \text{tr}_g \text{Ric} = \sum_i \text{Ric}(e_i, e_i) = \sum_{i,j} R(e_i, e_j, e_j, e_i).$$

As for sectional curvature, there is really only one convention for Ric and scal. A space with $\text{sec} \equiv k$ has constant Ricci curvature $\text{Ric} = (n-1)kg$ and scalar curvature $\text{scal} = n(n-1)k$.

In the backward convention for R , one has of course

$$\text{Ric}(X, Y) = \sum_i R(X, e_i, Y, e_i) = \text{tr}(Z \mapsto R(X, Z)Y)$$

The Ricci tensor is often turned into an endomorphism $\text{Ric} \in \text{End}(T)$ using the metric.

Curvature operator of the first kind. The Riemannian curvature tensor R gives rise to a symmetric endomorphism $\widehat{R} : \Lambda^2 T \rightarrow \Lambda^2 T$ via

$$\langle \widehat{R}(X \wedge Y), Z \wedge W \rangle = R(X, Y, Z, W),$$

where the inner product on 2-forms is given by

$$|X \wedge Y|^2 = g(X, X)g(Y, Y) - g(X, Y)^2.$$

\widehat{R} is called the *curvature operator of the first kind*. This way of defining \widehat{R} is what we call the *negative convention*, used for example by Friedrich, Semmelmann, etc. and we shall also use it unless otherwise stated.

In contrast, there is also the *positive convention* which differs by a sign. In this convention, \widehat{R} is related to sectional curvature simply by

$$\sec(\sigma) = \frac{\langle \widehat{R}\sigma, \sigma \rangle}{\langle \sigma, \sigma \rangle}$$

for decomposable bivectors σ , so \widehat{R} is positive whenever \sec is positive. The positive convention is used for example in [1, 2, 6].

We return to the negative convention. \widehat{R} may also directly defined by

$$\widehat{R}(X \wedge Y) = \frac{1}{2} \sum_i e_i \wedge R(X, Y)e_i.$$

Another formula is

$$(\widehat{R}\sigma)(X, Y) = \sum_{i < j} R(e_i, e_j, X, Y)\sigma(e_i, e_j) = \frac{1}{2} \sum_{i, j} R(e_i, e_j, X, Y)\sigma(e_i, e_j).$$

Here we see that this is $-\frac{1}{2}$ of the convention for \widehat{R} used in [3, 13, 14] (which we may call the *doubly positive convention*).

In the negative convention, the curvature operator operator on a space of $\sec \equiv k$ is

$$\widehat{R} = -k \text{Id}_{\Lambda^2}.$$

Using the inner product on Λ^2 defined above, one has

$$\widehat{g \otimes g} = 2 \text{Id}_{\Lambda^2},$$

so we recover the formula $R = -\frac{k}{2}g \otimes g$ from above.

Curvature operator of the second kind. The *curvature operator of the second kind* is another symmetric endomorphism $\mathring{R} : \text{Sym}^2 T \rightarrow \text{Sym}^2 T$ derived from R via

$$(\mathring{R}h)(X, Y) = \sum_i h(R(e_i, X)Y, e_i) = \sum_{i, j} R(X, e_i, e_j, Y)h(e_i, e_j).$$

(using the forward convention for R). This immediately implies

$$\mathring{R}g = \text{Ric}.$$

In the case of $\sec \equiv k$, we have

$$\mathring{R} = (n - 1)k \text{Id}_{\mathbb{R}g} - k \text{Id}_{\text{Sym}_0^2 T}.$$

We call this convention for \mathring{R} the *Ricci-like convention* or the *almost negative convention*. It is used by [1, 3]. The opposite sign convention (where $\langle \mathring{R}\cdot, \cdot \rangle$ is positive on $\text{Sym}_0^2 T$)

is called the *anti-Ricci-like convention* or *almost positive convention*, used for example in [4, 13, 14].

\mathring{R} preserves the space $\text{Sym}_0^2 T$ of *trace-free* tensors if and only if g is Einstein. Just like for sec or \widehat{R} , the curvature tensor R may be reconstructed from \mathring{R} . Other possible ways to contract R with 2-tensors are discussed in [3].

Because the operator \mathring{R} acts differently on g than on trace-free tensors (with different sign even for constant sectional curvature!), one sometimes considers instead the operator

$$\text{pr}_{\text{Sym}_0^2} \circ \mathring{R}|_{\text{Sym}_0^2}$$

and calls this the curvature operator of the second kind [11].

Other contractions with the curvature tensor. One may also contract a two-tensor $\alpha \in T \otimes T$ with other slots of the curvature tensor. If R^{ab} denotes the operator defined by contracting the a, b -slots of R with α (where $1 \leq a, b \leq 4$), then by the symmetries of the curvature tensors only R^{12} and $R^{23} = -R^{13}$ are actually of interest. If $h \in \text{Sym}^2 T$, then clearly

$$R^{12}h = 0, \quad R^{23}h = \mathring{R}h.$$

For $\sigma \in \Lambda^2 T$ on the other hand, we have

$$R^{12}\sigma = 2\widehat{R}\sigma, \quad R^{23}\sigma = -\widehat{R}\sigma.$$

using the first Bianchi identity for the second part.

The standard curvature endomorphism. Let (ω_k) be any orthonormal basis of $\Lambda^2 T$, for example $(e_i \wedge e_j)_{i < j}$. We identify $\Lambda^2 T \cong \mathfrak{so}(T)$ using the metric, i.e. via

$$(X \wedge Y)(Z) = g(X, Z)Y - g(Y, Z)X.$$

The *standard curvature element* is the element

$$q(R) = \sum_k \omega_k \widehat{R}(\omega_k) \in \mathfrak{Uso}(T)$$

in the universal enveloping algebra of $\mathfrak{so}(T)$. If $EM \rightarrow M$ is any vector bundle associated to the orthonormal frame bundle P , i.e. $EM = P \times_\rho E$ for some representation $\rho : \text{O}(n) \rightarrow E$, then the *standard curvature endomorphism* on EM is the fibrewise (symmetric) endomorphism $q(R)_{EM}$ associated to $q(R)$ through the infinitesimal representation of $\mathfrak{so}(T)$ on EM , i.e.

$$q(R)_{EM} = \sum_k \rho_*(\omega_k) \rho_*(\widehat{R}(\omega_k)).$$

This endomorphism² is also sometimes denoted $\mathcal{K}(R, EM)$ [2], or $-K$ [6], or Ric [15]. On a space with $\text{sec} \equiv k$, we have

$$q(R)_{EM} = k \text{Cas}_E^{\text{so}(n)}$$

where $\text{Cas}_E^{\text{so}(n)}$ is the (nonnegative) Casimir constant of the $O(n)$ -representation E . On the bundle of covariant p -tensors, $EM = \bigotimes^p T^*M$, we may succinctly write

$$(q(R)\alpha)(X_1, \dots, X_p) = \sum_{i,j} (R(e_j, X_i)\alpha)(X_1, \dots, X_{i-1}, e_j, X_{i+1}, \dots, X_p).$$

There is an uglier formula

$$(q(R)\alpha)_{i_1 \dots i_p} = \sum_k \text{Ric}_{ikj} \alpha_{i_1 \dots i_p}^j + \sum_{k \neq l} R_{ikjlm} \alpha_{i_1 \dots i_p}^{j \ m},$$

using Einstein summation convention. We have the following identities (it's possible to show them directly, but they also follow from the formula above):

$$\begin{aligned} q(R)_T &= \text{Ric}, \\ q(R)_{T \otimes T} &= \text{Ric}_* + 2R^{13}, \\ q(R)_{\Lambda^2 T} &= \text{Ric}_* + 2\hat{R}, \\ q(R)_{\text{Sym}^2 T} &= \text{Ric}_* - 2\hat{R}, \end{aligned}$$

where the Ricci endomorphism acts on tensors through the natural $\text{End}(T)$ -representation. In particular for $\alpha \in \text{End}(T)$, we have

$$\text{Ric}_* \alpha = \text{Ric} \circ \alpha + \alpha \circ \text{Ric}.$$

More relations are available in [2, Thm. B]. Specializing to p -forms or symmetric tensors, we have

$$\begin{aligned} q(R)\alpha &= \sum_{i,j} e^j \wedge (e_i \lrcorner R(e_i, e_j)\alpha), & \alpha \in \Lambda^p T^*M, \\ q(R)\alpha &= \sum_{i,j} e^j \odot (e_i \lrcorner R(e_i, e_j)\alpha), & \alpha \in \text{Sym}^p T^*M. \end{aligned}$$

The endomorphism $q(R)$ is precisely the curvature term appearing in the *Lichnerowicz Laplacian*

$$\Delta_L = \nabla^* \nabla + q(R).$$

Some authors also consider *Lichnerowicz-type Laplacians* where this curvature term is scaled by a positive constant [15]. The reason for this is the occurrence of terms of the type $\nabla^* \nabla + cq(R)$ in various Weitzenböck formulae.

²[1, §1.139, §1.143] introduces similar operators $c_\rho^2(R)$ and Γ (note the sign change in the second term of Γ according to differing sign conventions for R) and claims that $\Gamma = -2c_\rho^2(R)$. The mysterious factor of 2 probably comes from the inner product in Λ^2 .

The quantization map. Another convention for the standard curvature endomorphism coming from defining q as the *quantization map*

$$q : \text{Sym}^{\leq \bullet} \mathfrak{so}(T) \longrightarrow \mathfrak{U}^{\leq \bullet} \mathfrak{so}(T) : \quad X^{\odot k} \mapsto X^k$$

which is an isomorphism of filtered vector spaces. Using the metric duality, we understand the curvature tensor R as an element of $\text{Sym}^2 \mathfrak{so}(T)$ and write

$$R = \frac{1}{2} \sum_{k,l} \langle R, \omega_k \odot \omega_l \rangle \omega_k \odot \omega_l = \frac{1}{2} \sum_k \omega_k \odot \widehat{R}(\omega_k)$$

for an orthonormal basis (ω_k) of $\mathfrak{so}(T)$. So this $q(R)$ would be $\frac{1}{2}$ times the above!

Irreducible decomposition of the curvature tensor. The space of algebraic curvature tensors, i.e. the kernel of the Bianchi operator $b : \text{Sym}^2 \Lambda^2 T^* \rightarrow \Lambda^4 T^*$ with

$$b(R)(X, Y, Z, W) = R(X, Y, Z, W) + R(Y, Z, X, W) + R(Z, X, Y, W),$$

decomposes for $n \geq 5$ into three irreducible parts: the scalar part $\mathbb{R}g \otimes g$, the traceless Ricci part $\text{Sym}_0^2 T^* \otimes g$, and the Weyl part. (For $n = 4$, the Weyl part splits further into self-dual and anti-self-dual part. For $n = 3$, the Weyl part vanishes. For $n = 2$, both traceless Ricci and Weyl part vanish. For $n = 1$, there is no curvature at all.) The projections of a curvature tensor R to these parts are respectively given by

$$R = U + Z + W, \quad U = \frac{\text{scal}}{2n(n-1)} g \otimes g, \quad Z = \frac{1}{n-2} \text{Ric}^0 \otimes g.$$

The Weyl tensor W is annihilated by all contractions with g .

A digression on inner products and tensors

Recall that

$$\langle X \wedge Y, \alpha \rangle_{\Lambda^2 T} = \langle Y, X \lrcorner \alpha \rangle = \alpha(X, Y).$$

$$\langle e_i \wedge e_j, e_k \wedge e_l \rangle_{\Lambda^2 T} = \langle e_j, e_i \lrcorner (e_k \wedge e_l) \rangle = \delta_{ik} \delta_{jl} - \delta_{il} \delta_{jk}.$$

The two summands cannot be 1 simultaneously since $e_i \wedge e_i = 0$. If the first summand is 1, this means $\langle e_i \wedge e_j, e_i \wedge e_j \rangle = 1$. If the second summand is 1, this means that $\langle e_i \wedge e_j, e_j \wedge e_i \rangle = -1$. Thus $(e_i \wedge e_j)_{i < j}$ is an ONB of $\Lambda^2 T$.

For the symmetric square, we stipulate in the same vein

$$\langle X \odot Y, h \rangle_{\text{Sym}^2 T} \stackrel{!}{=} \langle Y, X \lrcorner h \rangle = h(X, Y).$$

$$\langle e_i \odot e_j, e_k \odot e_l \rangle_{\text{Sym}^2 T} \stackrel{!}{=} \langle e_j, e_i \lrcorner (e_k \odot e_l) \rangle = \delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk}.$$

The two summands are both 1 if $i = j = k = l$ and we get $\langle e_i \odot e_i, e_i \odot e_i \rangle = 2$. If only one of them is 1, this means $\langle e_i \odot e_j, e_i \odot e_j \rangle = \langle e_i \odot e_j, e_j \odot e_i \rangle = 1$, $i \neq j$. Thus $(\frac{1}{\sqrt{2}} e_i \odot e_i)_i \cup (e_i \odot e_j)_{i < j}$ is an ONB of $\text{Sym}^2 T$.

Similarly we define the inner product on $\text{Sym}^2 \mathfrak{so}(T)$. Interpreting R as an element of $\text{Sym}^2 \mathfrak{so}(T)^*$, we obtain

$$\sum_l \langle R, \omega_k \odot \omega_l \rangle \omega_l = \sum_l R(\omega_k, \omega_l) \omega_l = \sum_l \langle \widehat{R}(\omega_k), \omega_l \rangle \omega_l = \widehat{R}(\omega_k).$$

Thus

$$\sum_{k,l} \langle R, \omega_k \odot \omega_l \rangle \omega_k \odot \omega_l = \sum_k \omega_k \odot \widehat{R}(\omega_k).$$

On the other hand, since $(\frac{1}{\sqrt{2}}\omega_k \odot \omega_k)_k \cup (\omega_k \odot \omega_l)_{k<l}$ is an ONB of $\text{Sym}^2 \mathfrak{so}(T)$, we actually have

$$\begin{aligned} R &= \frac{1}{2} \sum_k \langle R, \omega_k \odot \omega_k \rangle \omega_k \odot \omega_k + \sum_{k<l} \langle R, \omega_k \odot \omega_l \rangle \omega_k \odot \omega_l = \frac{1}{2} \sum_{k,l} \langle R, \omega_k \odot \omega_l \rangle \omega_k \odot \omega_l \\ &= \frac{1}{2} \sum_k \omega_k \odot \widehat{R}(\omega_k). \end{aligned}$$

This reminds us of a similar calculation rule for Λ^2 , namely

$$\alpha = \frac{1}{2} \sum_i e_i \wedge \alpha(e_i).$$

Weitzenböck formulae

Having introduced the curvature endomorphism $q(R)$, it is time to show where it appears. Let ∇ denote the Levi-Civita connection of a Riemannian manifold (M, g) . We also denote with ∇ its extension to tensor bundles, as well as the connection on some generic vector bundle EM .

- On $\Omega^p(M)$,

$$d^*d + dd^* = \nabla^*\nabla + q(R).$$

- On $\mathcal{S}^p(M)$,

$$\delta\delta^* - \delta^*\delta = \nabla^*\nabla - q(R),$$

where $\delta^*h = \sum_i e^i \odot \nabla_{e_i} h$ (so that $L_{\alpha^\sharp} g = \delta^*\alpha$ for $\alpha \in \Omega^1(M)$).

- On $\Omega^p(M, EM)$,

$$\begin{aligned} (d^\nabla)^*d^\nabla + d^\nabla(d^\nabla)^* &= \nabla^*\nabla + q(R)_{\Lambda^p T^*} + \sum_k (\omega_k)_{\Lambda^p T^*} \otimes \widehat{R}(\omega_k)_E \\ &= \nabla^*\nabla + q(R)_{\Lambda^p T^* \otimes E} - q(R)_E - \sum_k \widehat{R}(\omega_k)_{\Lambda^p T^*} \otimes (\omega_k)_E, \end{aligned}$$

where $d^\nabla(\alpha \otimes v) = \sum_i (e^i \wedge \nabla_{e_i} \alpha \otimes v + e^i \wedge \alpha \otimes \nabla_{e_i} v)$.

- In particular, for $\alpha \in \Omega^1(M, TM)$,

$$((d^\nabla)^* d^\nabla + d^\nabla (d^\nabla)^*)\alpha = \nabla^* \nabla \alpha + \alpha \circ \text{Ric} + R^{13} \alpha.$$

- If (M, g) is Einstein, we recover on $\Omega^1(M, T^*M)$

$$(d^\nabla)^* d^\nabla + d^\nabla (d^\nabla)^* = \nabla^* \nabla \alpha + \frac{1}{2} q(R).$$

Weitzenböck formulae for *double forms* $\Omega^p(M, \Lambda^q T^*M)$ are available in [10].

Some examples

We have already seen spaces of constant sectional curvature (spherical or hyperbolic). Let us have a look at other symmetric spaces.

Complex projective space. The following is taken from [3, §5] and adapted to our conventions. Let $M = \mathbb{C}\mathbb{P}^n$ with its standard complex structure J and the Fubini–Study metric (normalized so that $1 \leq \text{sec} \leq 4$).

The curvature operator of the first kind (positive convention) may be written as

$$\widehat{R}\sigma = \sigma - J \circ \sigma \circ J - \langle J, \sigma \rangle J,$$

or, utilizing the decomposition $\Lambda^2 T^* = \mathbb{R}J \oplus \Lambda_0^{2,+} \oplus \Lambda^{2,-}$,

$$\widehat{R} = 2(n+1) \text{Id}_{\mathbb{R}J} + 2 \text{Id}_{\Lambda_0^{2,+}}.$$

For the curvature operator of the second kind (almost negative convention), we have in turn

$$\mathring{R}h = -\frac{1}{2}h + \frac{1}{2} \text{tr}(h)g - \frac{3}{2}J \circ h \circ J$$

and $\text{Sym}^2 T^* = \mathbb{R}g \oplus \text{Sym}_0^{2,+} \oplus \text{Sym}^{2,-}$, thus

$$\mathring{R} = (n+1) \text{Id}_{\mathbb{R}g} + \text{Id}_{\text{Sym}_0^{2,+}} - 2 \text{Id}_{\text{Sym}^{2,-}}.$$

Here the superscript \pm indicates the subspace of tensors commuting (resp. anticommuting) with J . We note that $\Lambda_0^{2,+} \cong \text{Sym}_0^{2,+} \cong \mathfrak{su}(n)$.

$\mathbb{C}\mathbb{P}^n$ is Einstein, i.e. $Z = 0$. For the scalar curvature, we have $U = \frac{n+1}{2n-1} g \otimes g$, so

$$\widehat{U} = \frac{2(n+1)}{2n-1} \text{Id}_{\Lambda^2}, \quad \mathring{U} = \frac{2(n^2-1)}{2n-1} \text{Id}_{\mathbb{R}g} - \frac{2(n+1)}{2n-1} \text{Id}_{\text{Sym}_0^2}.$$

Hence the Weyl parts are given by

$$\begin{aligned} \widehat{W} &= \frac{4(n^2-1)}{2n-1} \text{Id}_{\mathbb{R}J} + \frac{2(n-2)}{2n-1} \text{Id}_{\Lambda_0^{2,+}} - \frac{2(n+1)}{2n-1} \text{Id}_{\Lambda^{2,-}}, \\ \mathring{W} &= \frac{n+1}{2n-1} \text{Id}_{\mathbb{R}g} - \frac{3}{2n-1} \text{Id}_{\text{Sym}_0^{2,+}} - \frac{6n}{2n-1} \text{Id}_{\text{Sym}^{2,-}}. \end{aligned}$$

Cubing and tracing just for fun, we obtain

$$\begin{aligned}(2n-1)^3 \operatorname{tr}(\widehat{W}^3) &= 8(n-1)(n+1)n(2n-1)(4n^2+2n-11), \\ (2n-1)^3 \operatorname{tr}(\mathring{W}^3) &= -(n+1)(216n^4 - n^2 + 25n - 28).\end{aligned}$$

For $n = 3$ we obtain $\operatorname{tr}(\widehat{W}^3) = \frac{5952}{25}$ and $\operatorname{tr}(\mathring{W}^3) = -\frac{70136}{125}$.

The same analysis holds true on the dual (complex hyperbolic space $\mathbb{C}\mathbb{H}^n$), but with signs of the curvature reversed.

Some important results and references

- If $\mathring{R} > 0$ on $\operatorname{Sym}_0^2 T$ and $\delta R = 0$ (harmonic curvature), then $\operatorname{sec} > 0$ [7]. (alm. pos. conv.)
- If $\mathring{R} \geq 0$ on $\operatorname{Sym}_0^2 T$ and (M, g) is Einstein, then $\operatorname{sec} \equiv k$ [5]. (alm. pos. conv.)
- $q(R) \geq 0$ on all $\mathfrak{so}(n)$ -representations if and only if $\widehat{R} \geq 0$ [6, §4].
- If $\mathring{R} > 0$ on $\operatorname{Sym}_0^2 T$, then $\operatorname{sec} > 0$ [4]. (alm. pos. conv.)
- \mathring{R} preserves $\operatorname{Sym}_0^2 T$ if and only if (M, g) is Einstein.
- If (M, g) is compact, connected, orientable, with $\mathring{R} > 0$ on $\operatorname{Sym}_0^2 T$, then M is a real homology sphere [14]. Even better, it is diffeomorphic to a spherical space form [4].
- If (M, g) is compact, connected, orientable, with $\widehat{R} > 0$, then M is a real homology sphere [12].
- If $\widehat{R} \geq \delta$, then $\operatorname{sec} \geq \delta/2$ [13, 14]. (doubly pos. conv.)
- If $\mathring{R} \geq \delta$ on $\operatorname{Sym}_0^2 T$, then $\operatorname{sec} \geq \delta$ [14]. (alm. pos. conv.)
- If $\mathring{R} \geq 0$ on $\operatorname{Sym}^2 T$, then g is flat [14]. (alm. pos. conv.)
- If $\widehat{R} > 0$, then the Gauß–Bonnet integrand is positive [8].

Recheck these and clear up!!! especially for conventions.

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